



Microrobotics for Micromanipulation

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Microrobotics for Micromanipulation presents for the first time, in detail, the sector of robotics for handling objects of micrometer dimensions. At these dimensions, the behavior of objects is significantly different from the better known, higher scales, which leads us to implement solutions sometimes radically different from those most commonly used. This book details the behavior of objects at the micrometer scale and suitable robotics solutions, in terms of actuators, grippers, manipulators, environmental perception and microtechnology. This book includes corrected exercises, enabling engineers, students and researchers to familiarize themselves with this emerging area and to contribute to its development through scientific measures.

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